

Can we use the nearby velocity distribution to constrain the properties of the bar and the spiral arms of the MW?

Gaia capabilities

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Sevres, 7th-11th June 2010

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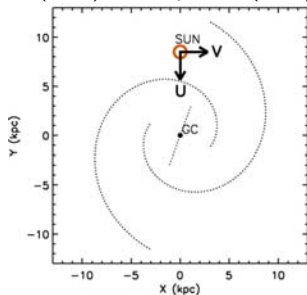
Dr. Octavio Valenzuela
Dra. Barbara Pichardo



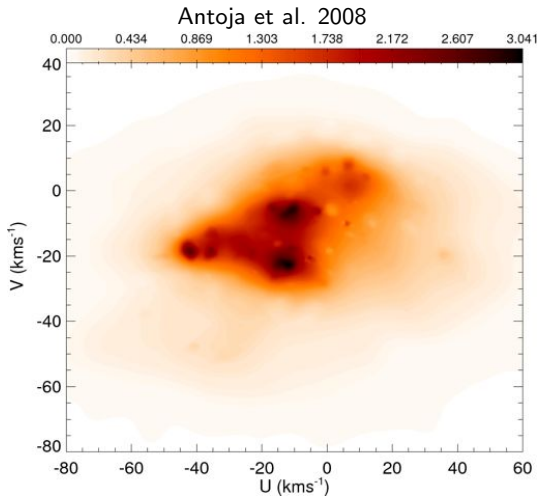
- 1 INTRODUCTION
- 2 TEST PARTICLE ORBIT SIMULATIONS
- 3 GAIA CAPABILITIES

What are moving groups?

- U V W for 24000 stars:
Nordström et al. (2004); Asiain et al. (1999a); Torra et al. (2000); Reid et al. (2002); Bochanski et al. (2005); Famaey et al. (2005)

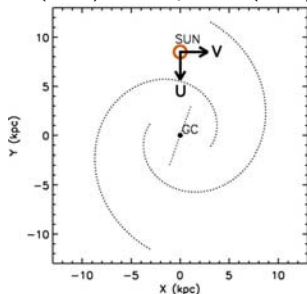


- Wavelet denoising

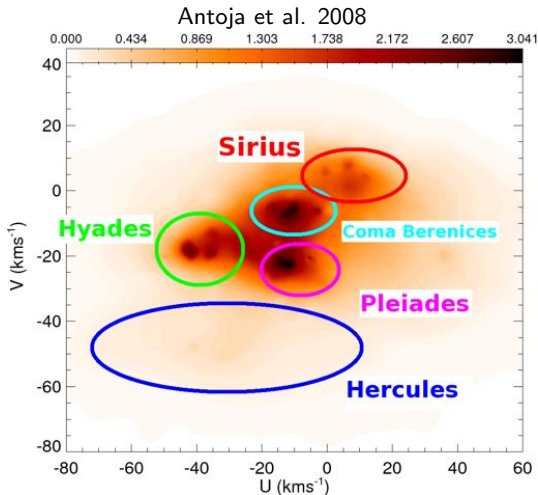


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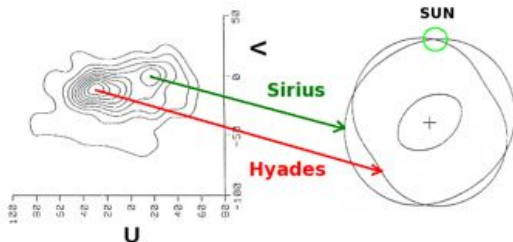


- Wavelet denoising



Interest of moving groups

Orbital and resonant effects of the MW spiral arms and bar



Kalnajs (1991)

Only for particular
bar orientation and
pattern speed!!

MOVING GROUPS:
tool to constrain the properties of the bar and the spiral arms!

SPIRAL ARMS & BAR:

- Mass or strength?
- Pattern speed?
- Orientation?



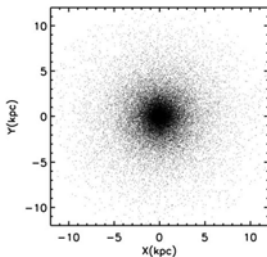
Outline

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Simulation method

- **Initial Conditions:**

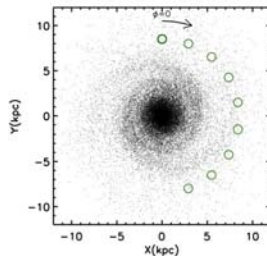
- IC1 cold disk
- IC2 warm disk
- IC3 hot disk



Integration of
test particle
orbits



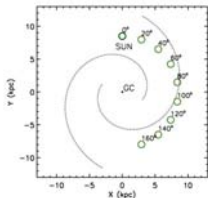
- **Analysis of the velocity distribution**



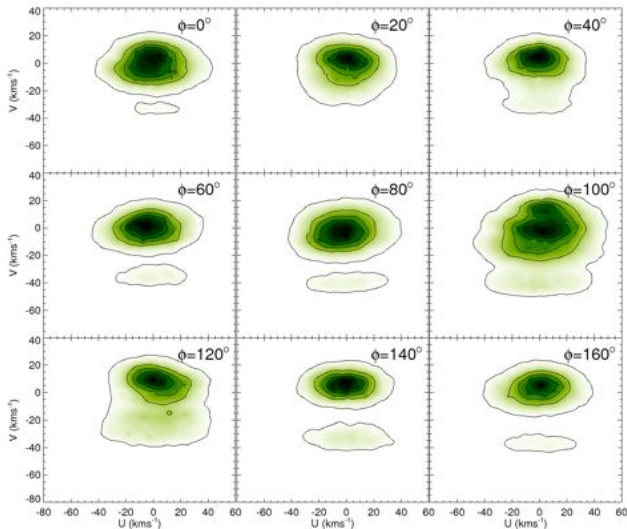
- **Potential Model for the MW:**

AXISYMMETRIC
SPIRAL ARMS (Pichardo et al. 2003b)
BAR (Pichardo et al. 2004)

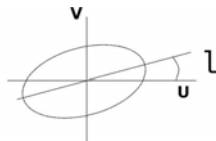
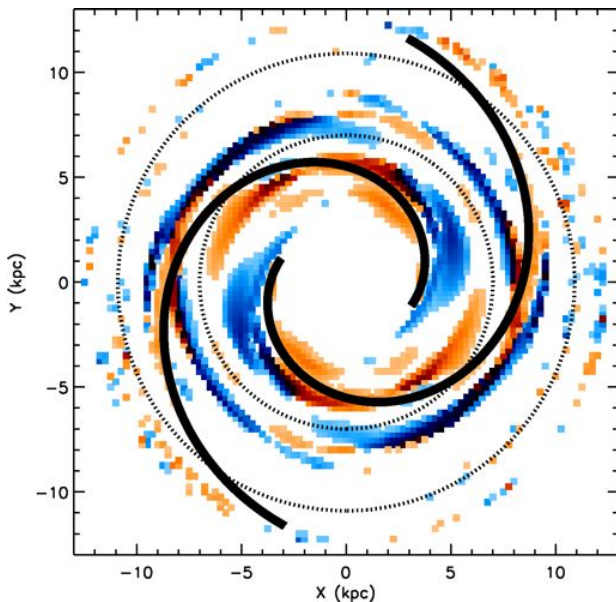
Imprints of the spiral arms IC1



- Strong imprints on the velocity plane, specially near the arms
- Branches resembling the observed ones
- Crowding at $V \sim -40 \text{ km s}^{-1}$, not only the bar!



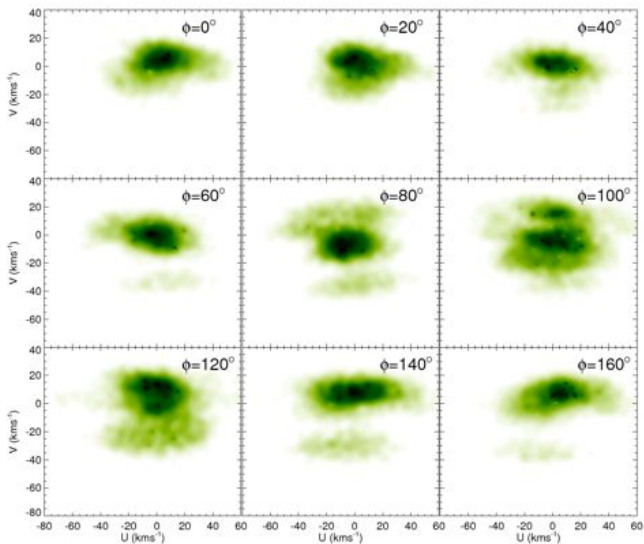
Imprints of the spiral arm: vertex deviation



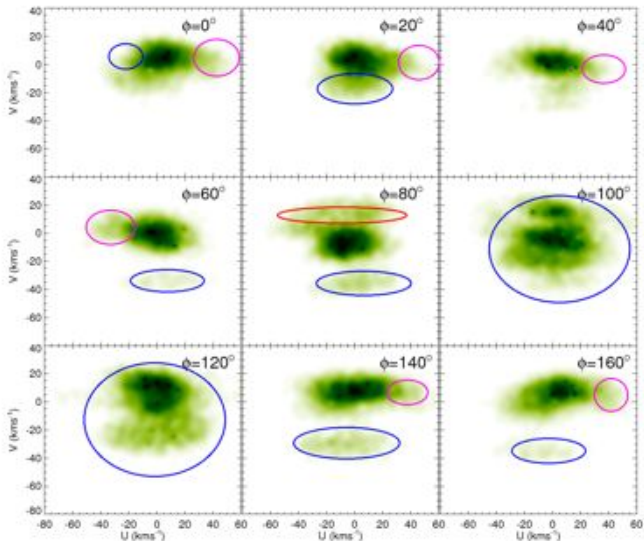
$$l < 0$$

$$l > 0$$

Imprints of the spiral-bar model IC1



Imprints of the spiral-bar model IC1



SPIRAL ARMS
BAR
NEW

Direct spiral arm kinematic perturbation

Observationally:

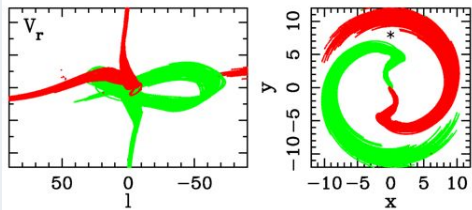
Monguio et al. 2010, in prep.

Theoretically:

Romero-Gomez et al. 2010, in prep.

Testing kinematic perturbation
of different models:

- Lin&Shu perturbation?
- Invariant manifolds of the bar potential?



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Particular cases:

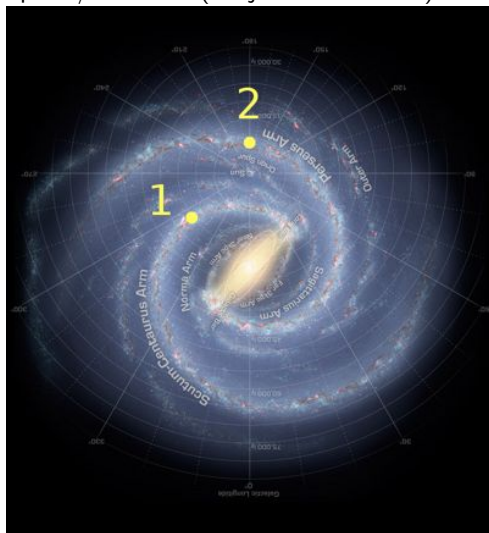
- 1) Scutum-Centaurus tangency
- 2) Perseus arm in the anti-center

Why these positions?

- Particularly rich in resonant substructure
- Regions that experience the spiral arm perturbation

SIMULATIONS
WITH SPIRAL ARMS
+
GAIA EXPECTED ACCURACIES

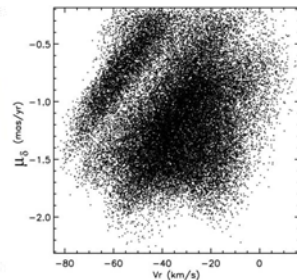
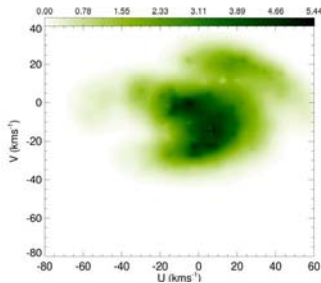
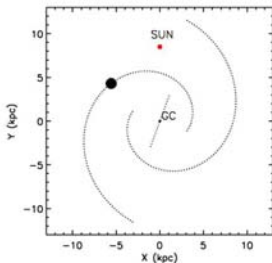
Spitzer/GLIMPSE (Benjamin et al. 2005)



Scutum-Centaurus tangency

$$l = 305^\circ, \beta = 0^\circ,$$

$$\text{dist} = 6.9 \text{ kpc}$$



K4-5 III
 $M_V, (V-I)_i, A_V, A_I$

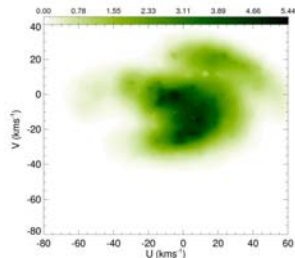
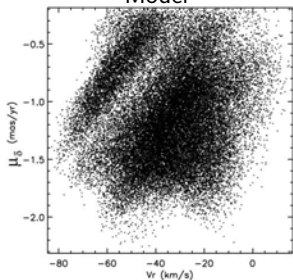


$G \sim 18$
 $e_\pi \sim 90 \mu\text{as}$ (62% !!)
 $e_\mu \sim 50 \mu\text{as/yr}$
 No radial velocities!!

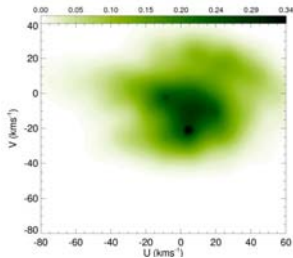
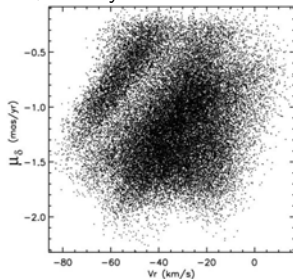
- Radial velocities needed
- Better distances

Scutum-Centaurus tangency

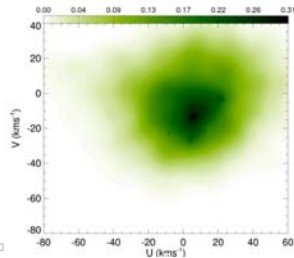
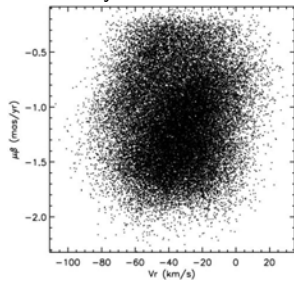
Model



+ GAIA errors
+ survey $e_{V_r} = 2 \text{ km s}^{-1}$



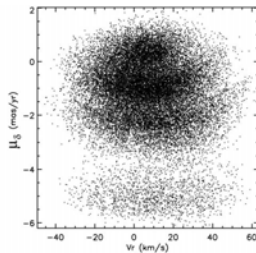
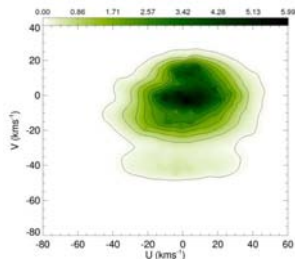
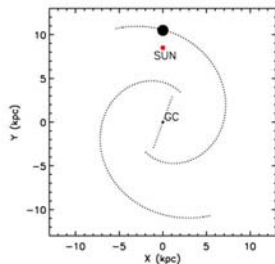
+ GAIA errors
+ survey $e_{V_r} = 10 \text{ km s}^{-1}$



Perseus arm in the anti-centre

$$l = 180^\circ, \beta = 0^\circ,$$

$$\text{dist} = 2.0 \text{ kpc}$$



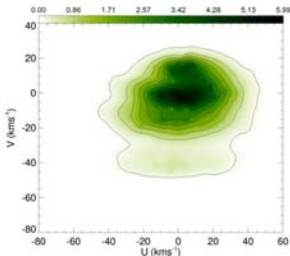
$M_V, (V-I)_i,$
 A_V, A_I

\Rightarrow

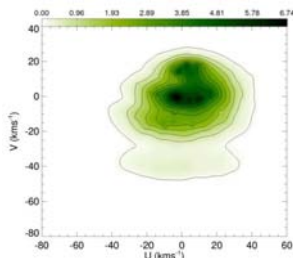
ST	G	$e_\pi (\mu as)$	$e_\mu (\mu as)$	$e_{VR} (\text{km s}^{-1})$
B5 V	13	8 (2%)	4	10
K5 III	13	8 (2%)	4	1
A5 V	15	23(5%)	12	20

Perseus arm in the anti-centre

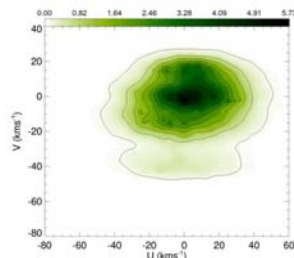
Model



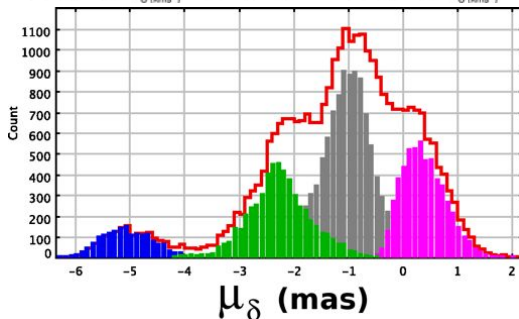
+ GAIA errors (K5 III)



+ GAIA errors (B5 V)



Very good job
in the Perseus arm!



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